

2010 HIPACC Astro-Computing Summer School

*Galaxy Simulations Using
the N-Body/SPH code
GADGET*

T.J. Cox (Carnegie Observatories)

Project 1.1: Code Optimization

PBS batchscript :

```
#!/bin/sh
#PBS -q batch
#PBS -N Sbc
#PBS -l nodes=2:ppn=2
#PBS -o Sbc.out
#PBS -e Sbc.err
#PBS -V
#PBS -M tcox@obs.carnegiescience.edu
#PBS -m abe

cd /home/hipacc-5/Sbc/

mpirun -v -machinefile $PBS_NODEFILE -np 4 ./Gadget2 Sbc.txt > output0.txt
```

While you're free to email me, your batch scripts should really contain your email address.

Outline

1. ~~Who am I and what am I doing here? My perspective, my science, and where my focus will be this week~~
2. ~~An overview of GADGET projects (+other practical + I hope information)~~
3. A brief overview of GADGET
4. Adding “Astrophysics” to GADGET
5. Loose Ends ... data structures, analysis, and visualization (w/ P. Hopkins)
6. What’s next? (higher resolution, new models, and Arepo: the next generation of code)

3. GADGET: A Brief Intro

- 3.1 The Monte Carlo, N-body approach to solving the CBE
- 3.2 Gravity calculation
- 3.3 Integration and time-steps
- 3.4 Including hydrodynamics with SPH
- 3.5 The steps Gadget takes to accomplish the above
- 3.7 Data Structures within Gadget
- 3.8 Modes of Gadget
- 3.9 The remaining compile-time and run-time parameters
- 3.10 Odd and Ends ... Questions

Gadget (and other N-body)

Resources

- Gadget Manual - comes with the public download
- Gadget papers: 1 (Springel, Yoshida, & White 2000) and 2 (Springel 2005)
- Hernquist & Katz (1989): TreeSPH (basically, Gadget version 0)
- Josh Barnes: (Barnes & Hut 1985, Barnes' website, his 1996 Saas-Fee lectures)
- Volker Springel's 2009 IAS Summer School lectures (very technical, but a thorough introduction to the nitty-gritty)
- Binney & Tremaine, *Galactic Dynamics* (1987)
- Hands-on experience digging within the code, modifying it, screwing it up and trying to figure out how to fix it again

3.1 Monte Carlo Approach to solving the Collisionless Boltzmann Equation

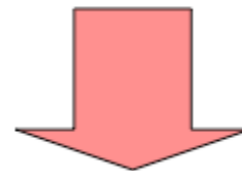
Galaxies are collisionless systems; $t_{\text{relax}} \sim (N/8 \ln \Lambda) t_{\text{cross}}$ (see Binney & Tremaine for a nice discussion of this)

BASIC MONTE-CARLO IDEA

Poisson-Vlasov System

$$\frac{df}{dt} = \frac{\partial f}{\partial t} + \frac{\partial f}{\partial \mathbf{x}} \cdot \mathbf{v} + \frac{\partial f}{\partial \mathbf{v}} \cdot \left(-\frac{\partial \Phi}{\partial \mathbf{x}} \right) = 0$$
$$\nabla^2 \Phi(\mathbf{x}, t) = 4\pi G \int f(\mathbf{x}, \mathbf{v}, t) d\mathbf{v}$$

Collisionless Boltzmann equation



N-body System

$$\ddot{\mathbf{x}}_i = -\nabla_i \Phi(\mathbf{x}_i)$$
$$\Phi(\mathbf{x}) = -G \sum_{j=1}^N \frac{m_j}{[(\mathbf{x} - \mathbf{x}_j)^2 + \epsilon^2]^{1/2}}$$

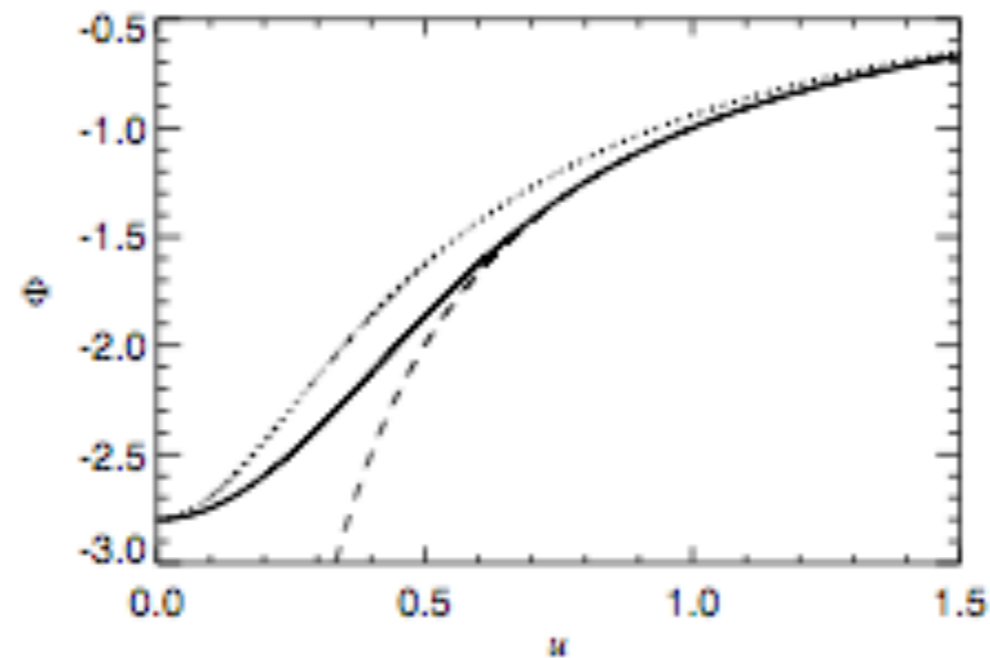
need large **N**

3.1 Mont Carlo Approach to solving the Collisionless Boltzmann Equation

N-body System

$$\ddot{\mathbf{x}}_i = -\nabla_i \Phi(\mathbf{x}_i)$$

$$\Phi(\mathbf{x}) = -G \sum_{j=1}^N \frac{m_j}{[(\mathbf{x} - \mathbf{x}_j)^2 + \epsilon^2]^{1/2}}$$



Gravitational softening within some scale accounts for finite N. Gadget uses spline kernel.

3.1 Mont Carlo Approach to solving the Collisionless Boltzmann Equation

What should the gravitational softening be?
unfortunately, this isn't an easy question to answer.

- * To zeroth order, collisionless criterion suggest it should depend on N and t_{cross}
- * Cosmological simulations often employ simple criterion based upon the mean inter-particle spacing ($\sim 1/20$ th or so)
- * Power et al. (2003) present a nice discussion and argue for values based on N and the size of the DM halo

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While these estimates are useful starting points, there is NO definitive way to know what the softening should be outside of performing detailed numerical experiments.

3.1 Mont Carlo Approach to solving the Collisionless Boltzmann Equation

What should the gravitational softening be?
unfortunately, this isn't an easy question to answer.

Compile-time options from within the Makefile:

```
OPT += -DUNEQUALSOFTENINGS
```

Parameter file options:

```
% Softening lengths
```

```
MinGasHsm1Fractional 0.25
```

```
SofteningGas          0.1
```

```
SofteningHalo         0.2
```

```
SofteningDisk         0.1
```

```
SofteningBulge        0.1
```

```
SofteningStars        0.1
```

```
SofteningBndry        0.1
```

```
SofteningGasMaxPhys   0.1
```

```
SofteningHaloMaxPhys  0.2
```

```
SofteningDiskMaxPhys  0.4
```

```
SofteningBulgeMaxPhys 0.1
```

```
SofteningStarsMaxPhys 0.1
```

```
SofteningBndryMaxPhys 0.1
```

3.1 Mont Carlo Approach to solving the Collisionless Boltzmann Equation

What should the number of particles, N , be?

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*The answer to this question is easy - as large as possible!

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What should the number of particles, N , be?

*The answer to this question is easy - as large as possible!

Of course, $N_{\text{simulated}}$ will always (at least for the near future) be much smaller than N_{actual} , so the only way to know what affect the choice of N plays on your results is to perform detailed numerical experiments.

3.1 Mont Carlo Approach to solving the Collisionless Boltzmann Equation

What should the number of particles, N , be?

An example:

A current “typical” run (moderately high resolution, but quick enough to run numerous runs) has 1 million DM particles, 300k gas and collisionless disk particles, and 100k bulge particles. The gravitational softening was 70 pc for all baryonic components and 250 pc for the DM.

-> isolated galaxy evolved for 3 Gyr: 5 days on 8 processors

-> major merger between two of these: 45 days on 32 processors

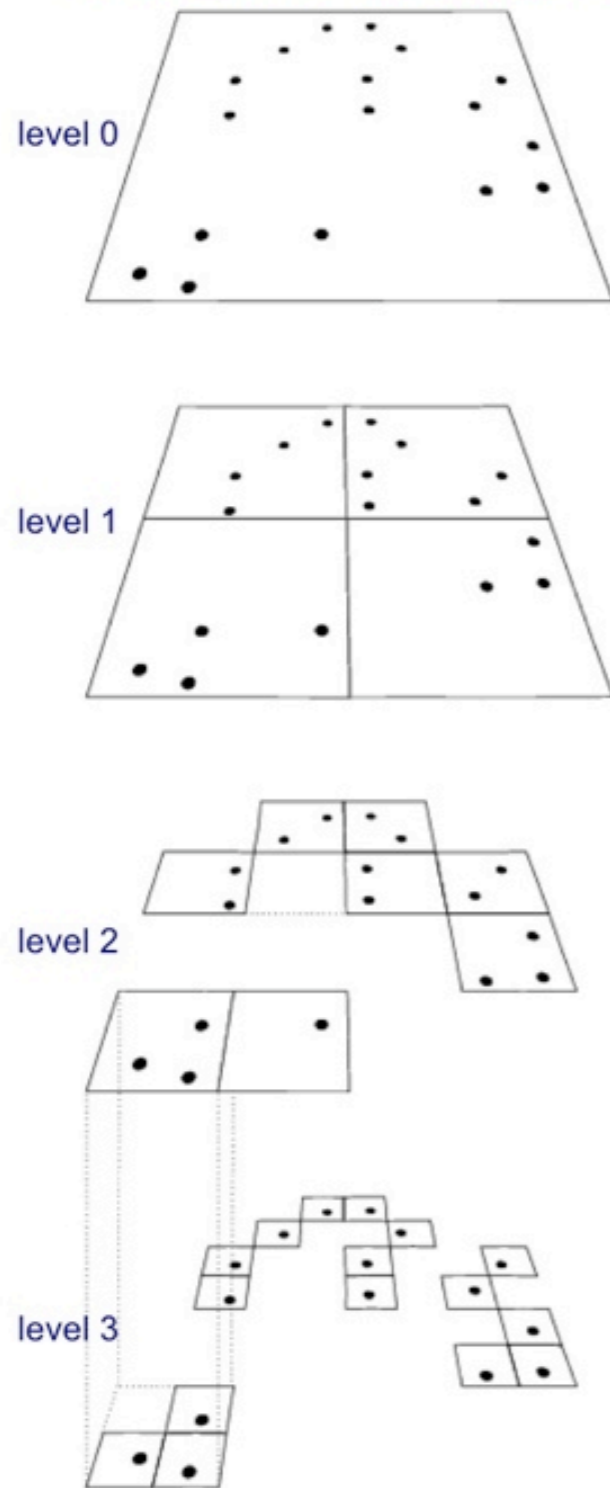
Highest resolution mergers:

25 million total / 1 million gas - ~4 months to completion (128 processors)

15 million total / 3 million gas - still running after 6 months (48 processors)

3.3 Gravity calculation

Oct-tree in two dimensions



Tree algorithms

Idea: Use hierarchical multipole expansion to account for distant particle groups

$$\Phi(\mathbf{r}) = -G \sum_i \frac{m_i}{|\mathbf{r} - \mathbf{x}_i|}$$

We expand:

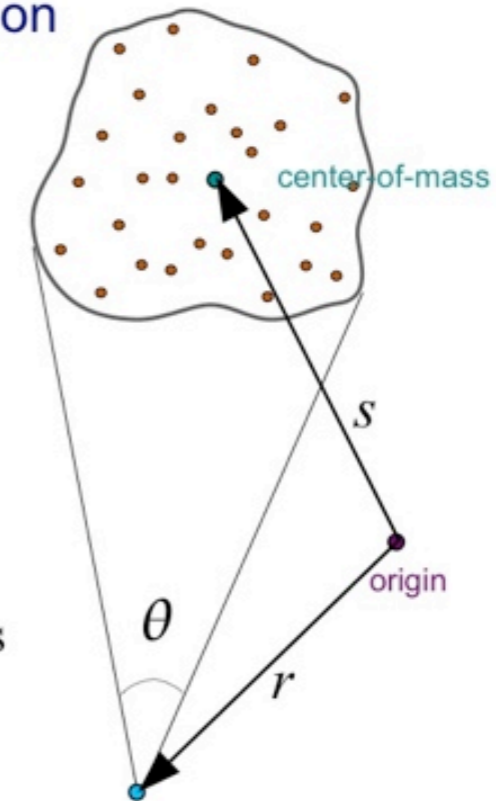
$$\frac{1}{|\mathbf{r} - \mathbf{x}_i|} = \frac{1}{|(\mathbf{r} - \mathbf{s}) - (\mathbf{x}_i - \mathbf{s})|}$$

for $|\mathbf{x}_i - \mathbf{s}| \ll |\mathbf{r} - \mathbf{s}|$ $\mathbf{y} \equiv \mathbf{r} - \mathbf{s}$

and obtain:

$$\frac{1}{|\mathbf{y} + \mathbf{s} - \mathbf{x}_i|} = \frac{1}{|\mathbf{y}|} - \frac{\mathbf{y} \cdot (\mathbf{s} - \mathbf{x}_i)}{|\mathbf{y}|^3} + \frac{1}{2} \frac{\mathbf{y}^T [3(\mathbf{s} - \mathbf{x}_i)(\mathbf{s} - \mathbf{x}_i)^T - \mathbf{I}(\mathbf{s} - \mathbf{x}_i)^2] \mathbf{y}}{|\mathbf{y}|^5} + \dots$$

the dipole term vanishes when summed over all particles in the group



3.3 Gravity calculation

The multipole moments are computed for each node of the tree

Monpole moment:

$$M = \sum_i m_i$$

Quadrupole tensor:

$$Q_{ij} = \sum_k m_k \left[3(\mathbf{x}_k - \mathbf{s})_i (\mathbf{x}_k - \mathbf{s})_j - \delta_{ij} (\mathbf{x}_k - \mathbf{s})^2 \right]$$

Resulting potential/force approximation:

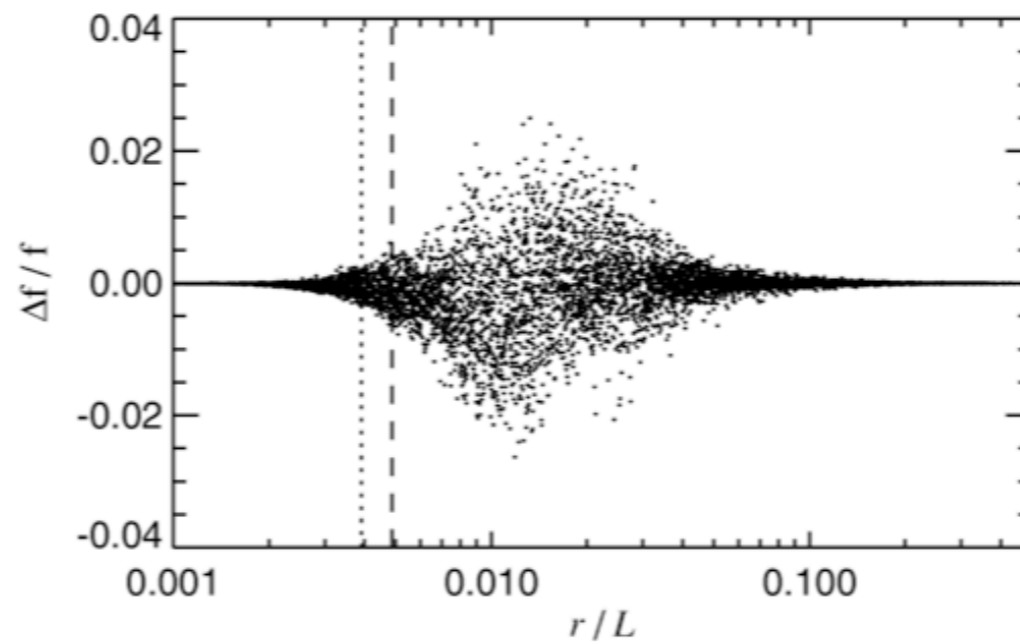
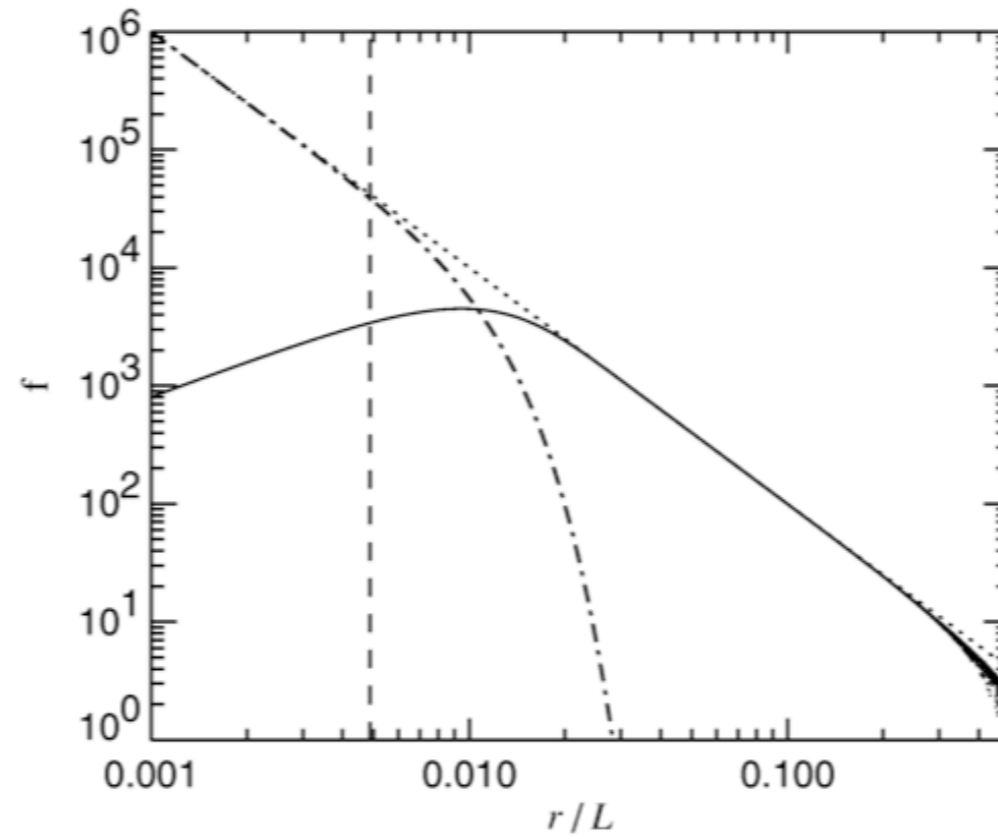
$$\Phi(\mathbf{r}) = -G \left[\frac{M}{|\mathbf{y}|} + \frac{1}{2} \frac{\mathbf{y}^T \mathbf{Q} \mathbf{y}}{|\mathbf{y}|^5} \right]$$

For a single force evaluation, not N single-particle forces need to be computed, but **only of order $\log(N)$ multipoles**, depending on the opening angle.

- The tree algorithm has no intrinsic restrictions for its dynamic range
- force accuracy can be conveniently adjusted to desired level
- the speed does depend only very weakly on clustering state
- geometrically flexible, allowing arbitrary geometries

3.3 Gravity calculation

Gadget2 can also calculate gravitational forces via the TreePM method.



3.3 Gravity calculation

Compile-time options from within the Makefile:

```
#----- TreePM Options
#OPT += -DPMGRID=128
#OPT += -DPLACEHIGHRESREGION=3
#OPT += -DENLARGEREGION=1.2
#OPT += -DASMTH=1.25
#OPT += -DRCUT=4.5
```

Parameter file options:

```
% Tree algorithm, force accuracy, domain update frequency
```

```
ErrTolTheta          0.5
TypeOfOpeningCriterion 1
ErrTolForceAcc       0.005
```

```
TreeDomainUpdateFrequency 0.1
```

3.2 Integration and time-step issues

Leapfrog integrator (requires a single force computation, conserves phase space/symplectic, and is time reversible)

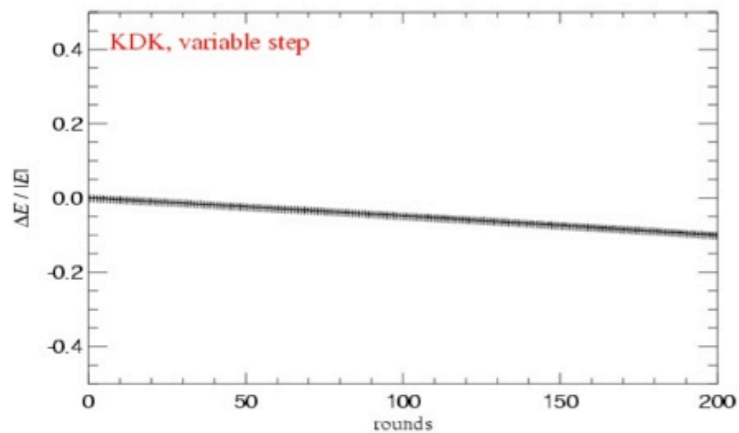
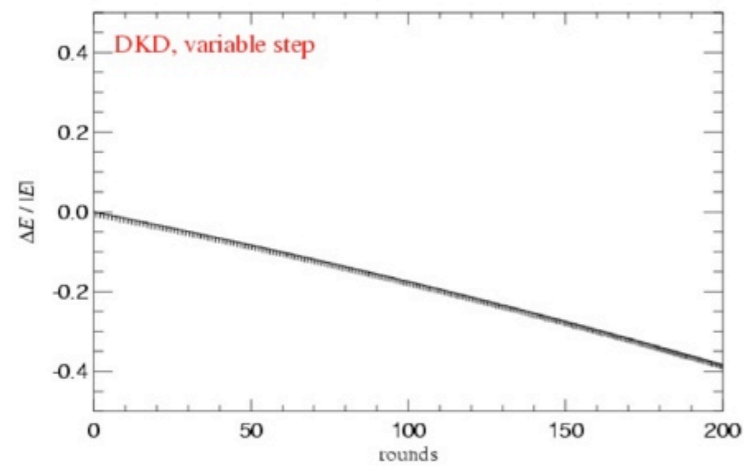
$$\begin{aligned}\mathbf{r}_{n+1/2} &= \mathbf{r}_n + \frac{1}{2}\tau\mathbf{v}_n, && \text{drift} \\ \mathbf{v}_{n+1} &= \mathbf{v}_n + \tau\mathbf{a}(\mathbf{r}_{n+1/2}), && \text{kick} \\ \mathbf{r}_{n+1} &= \mathbf{r}_{n+1/2} + \frac{1}{2}\tau\mathbf{v}_{n+1}, && \text{drift}\end{aligned}$$

see Quinn et al. (1997) for much more detail and a much better description

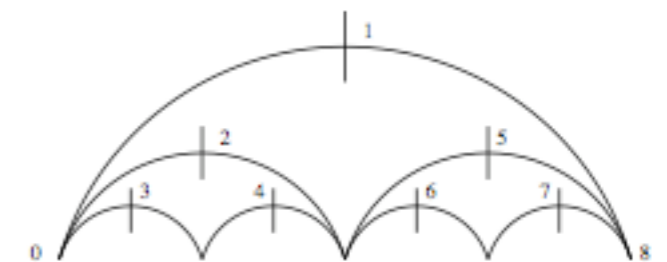
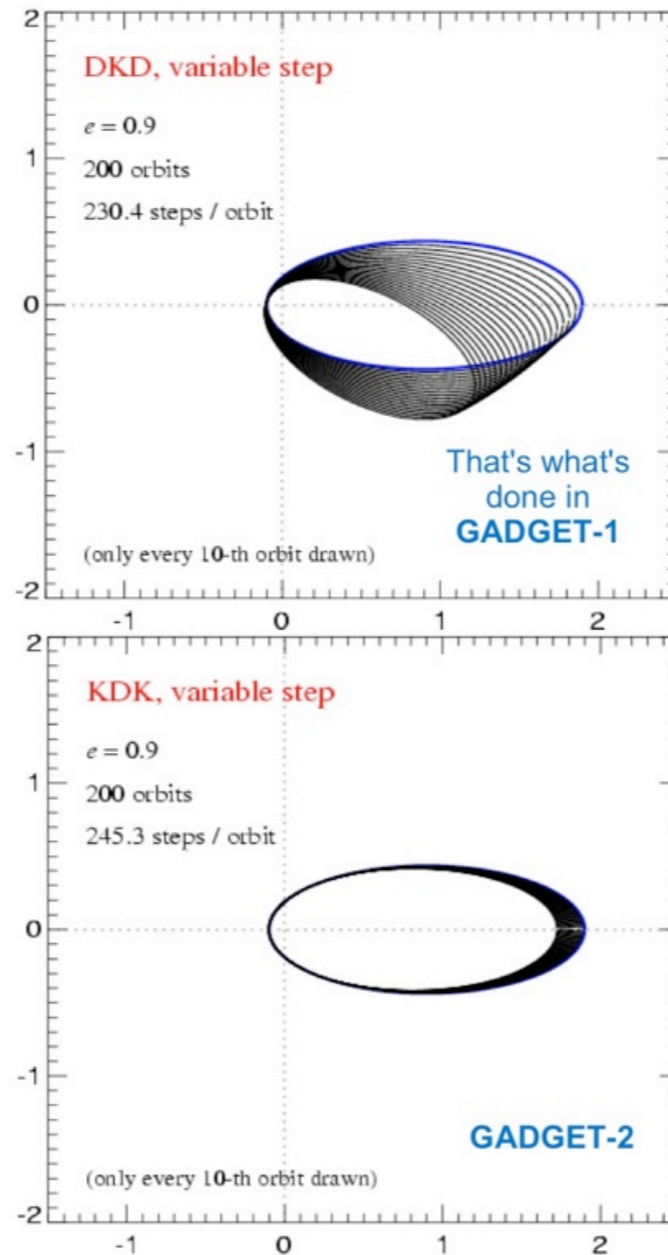
3.2 Integration and time-step issues

When an adaptive timestep is used, much of the symplectic advantage is lost

INTEGRATING THE KEPLER PROBLEM



→ Going to KDK reduces the error by a factor 4, at the same cost !



the situation can be improved with timesteps chosen in a factor of 2 hierarchy, see, e.g., Quinn et al. (1997)

3.2 Integration and time-step issues

Compile-time options from within the Makefile:

```
#----- Time integration options
OPT += -DSYNCHRONIZATION
#OPT += -DFLEXSTEPS
#OPT += -DPSEUDOSYMMETRIC
#OPT += -DNOSTOP_WHEN_BELOW_MINTIMESTEP
#OPT += -DNOPMSTEPADJUSTMENT
```

Parameter file options:

% Accuracy of time integration

ErrToLIntAccuracy 0.0025

CourantFac 0.15

MaxSizeTimestep 0.01

MinSizeTimestep 0.0

$$\Delta t_{\text{grav}} = \min \left[\Delta t_{\text{max}}, \left(\frac{2\eta\epsilon}{|a|} \right)^{1/2} \right]$$

$$\Delta t_i^{(\text{hyd})} = \frac{C_{\text{courant}} h_i}{\max_j (c_i + c_j - 3w_{ij})}$$

3.2 Integration and time-step issues

Compile-time options from within the Makefile:

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ErrToIntAccuracy 0.0025

CourantFac 0.15

MaxSizeTimestep 0.01

MinSizeTimestep 0.0

TypeOfTimestepCriterion 0

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obsolete in Gadget 2

3.2 Integration and time-step issues

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```

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MaxSizeTimestep 0.01

MinSizeTimestep 0.0

Be Careful with this default value!

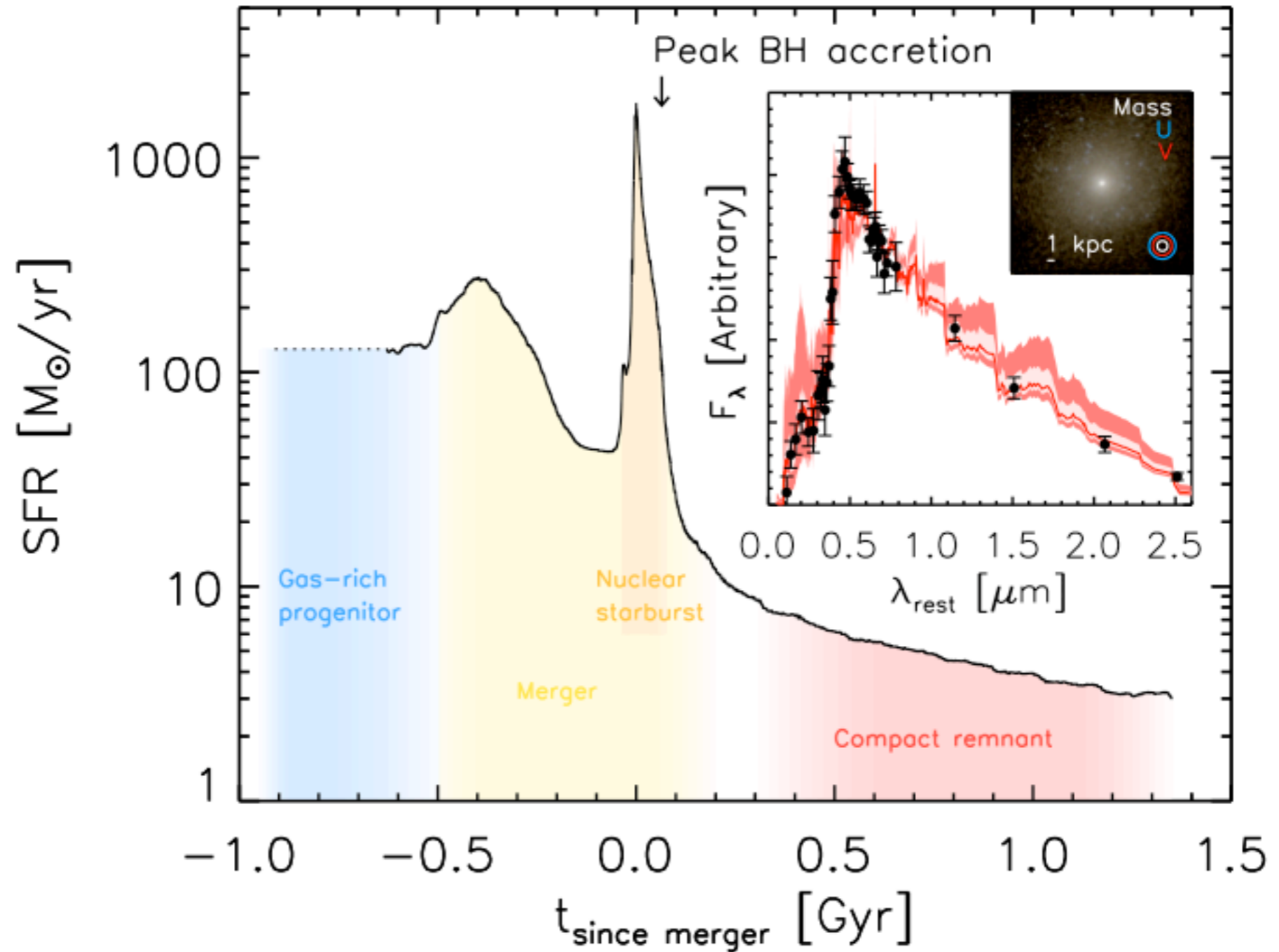
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3.2 Integration and time-step issues

cautionary tale:

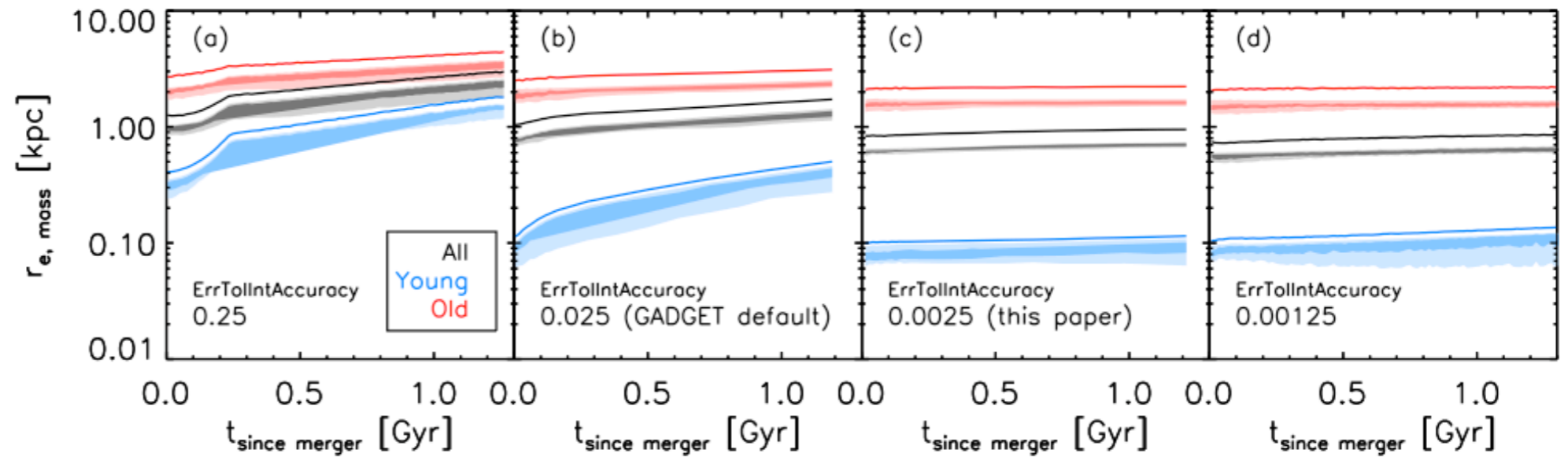
Wuyts et al. (2010) have studied the compact remnants forms from $z \sim 2$ gas-rich mergers



3.2 Integration and time-step issues

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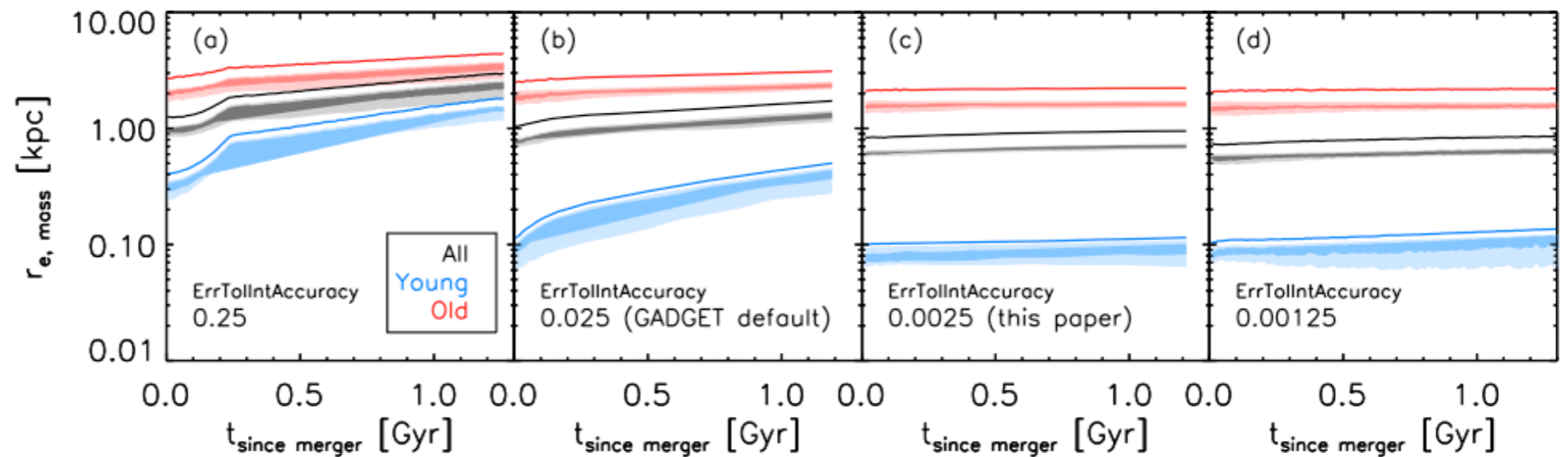
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3.2 Integration and time-step issues

cautionary tale:

Wuyts et al. (2010) have studied the compact remnants forms from $z \sim 2$ gas-rich mergers



When looking at structure at/near your resolution limit, you need high integration accuracy!

3.4 Including hydrodynamics via SPH

* Nice discussion from Tom Abel yesterday about various perils of SPH and the new formulation rpSPH

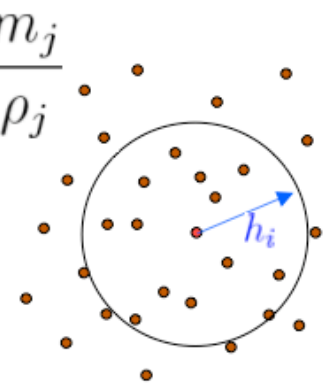
* And from Tom Quinn this morning so this will be brief.

Kernel interpolant of an arbitrary function:

$$\langle A(\mathbf{r}) \rangle = \int W(\mathbf{r} - \mathbf{r}', h) A(\mathbf{r}') d^3r'$$

If the function is only known at a set of discrete points, we approximate the integral as a sum, using the replacement:

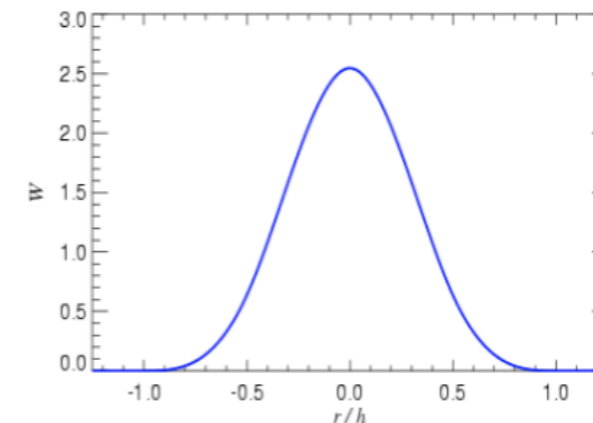
$$d^3r' \mapsto \frac{m_j}{\rho_j}$$

$$\langle A_i \rangle = \sum_{j=1}^N \frac{m_j}{\rho_j} A_j W(\mathbf{r}_{ij}; h_i)$$


This leads to the SPH density estimate, for $A_i = \rho_i$

$$\rho_i = \sum_{j=1}^N m_j W(|\mathbf{r}_{ij}|, h_i)$$

$$W(u) = \frac{8}{\pi} \begin{cases} 1 - 6u^2 + 6u^3, & 0 \leq u \leq \frac{1}{2}, \\ 2(1 - u)^3, & \frac{1}{2} < u \leq 1, \\ 0, & u > 1. \end{cases}$$



3.4 Including hydrodynamics via SPH

Smoothed estimate for the velocity field:

$$\langle \mathbf{v}_i \rangle = \sum_j \frac{m_j}{\rho_j} \mathbf{v}_j W(\mathbf{r}_i - \mathbf{r}_j)$$

Velocity divergence can now be readily estimated:

$$\nabla \cdot \mathbf{v} = \nabla \cdot \langle \mathbf{v}_i \rangle = \sum_j \frac{m_j}{\rho_j} \mathbf{v}_j \nabla_i W(\mathbf{r}_i - \mathbf{r}_j)$$

But alternative (and better) estimates are possible also:

Invoking the identity

$$\rho \nabla \cdot \mathbf{v} = \nabla \cdot (\rho \mathbf{v}) - \mathbf{v} \cdot \nabla \rho$$

one gets a “pair-wise” formula:

$$\rho_i (\nabla \cdot \mathbf{v})_i = \sum_j m_j (\mathbf{v}_j - \mathbf{v}_i) \nabla_i W(\mathbf{r}_i - \mathbf{r}_j)$$

3.4 Including hydrodynamics via SPH

BASIC HYDRODYNAMICAL EQUATIONS

Euler equation: $\frac{d\mathbf{v}}{dt} = -\frac{\nabla P}{\rho} - \nabla\Phi$

Continuity equation: $\frac{d\rho}{dt} + \rho\nabla \cdot \mathbf{v} = 0$

First law of thermodynamics: $\frac{du}{dt} = -\frac{P}{\rho}\nabla \cdot \mathbf{v} - \frac{\Lambda(u, \rho)}{\rho}$

Equation of state of an ideal monoatomic gas: $P = (\gamma - 1)\rho u, \quad \gamma = 5/3$

$$\frac{d\mathbf{v}_i}{dt} = -\sum_{j=1}^N m_j \left(\frac{P_i}{\rho_i^2} + \frac{P_j}{\rho_j^2} \right) \nabla_i \bar{W}_{ij}$$

+ Π_{ij} Artificial viscosity

automatic

$$\frac{du_i}{dt} = \frac{1}{2} \sum_{j=1}^N m_j \left(\frac{P_i}{\rho_i^2} + \frac{P_j}{\rho_j^2} \right) \mathbf{v}_{ij} \cdot \nabla_i \bar{W}_{ij}$$

+ Π_{ij}

$$P_i = (\gamma - 1)\rho_i u_i$$

3.4 Including hydrodynamics via SPH

As both Tom Abel and Tom Quinn have mentioned, there are many formulations of SPH, specifically how you symmetrize the Kernel or the pressure terms.

Gadget uses an entropy formulation derived with a variational approach that alleviates some of the problems associated with varying smoothing lengths (see Springel & Hernquist 2002).

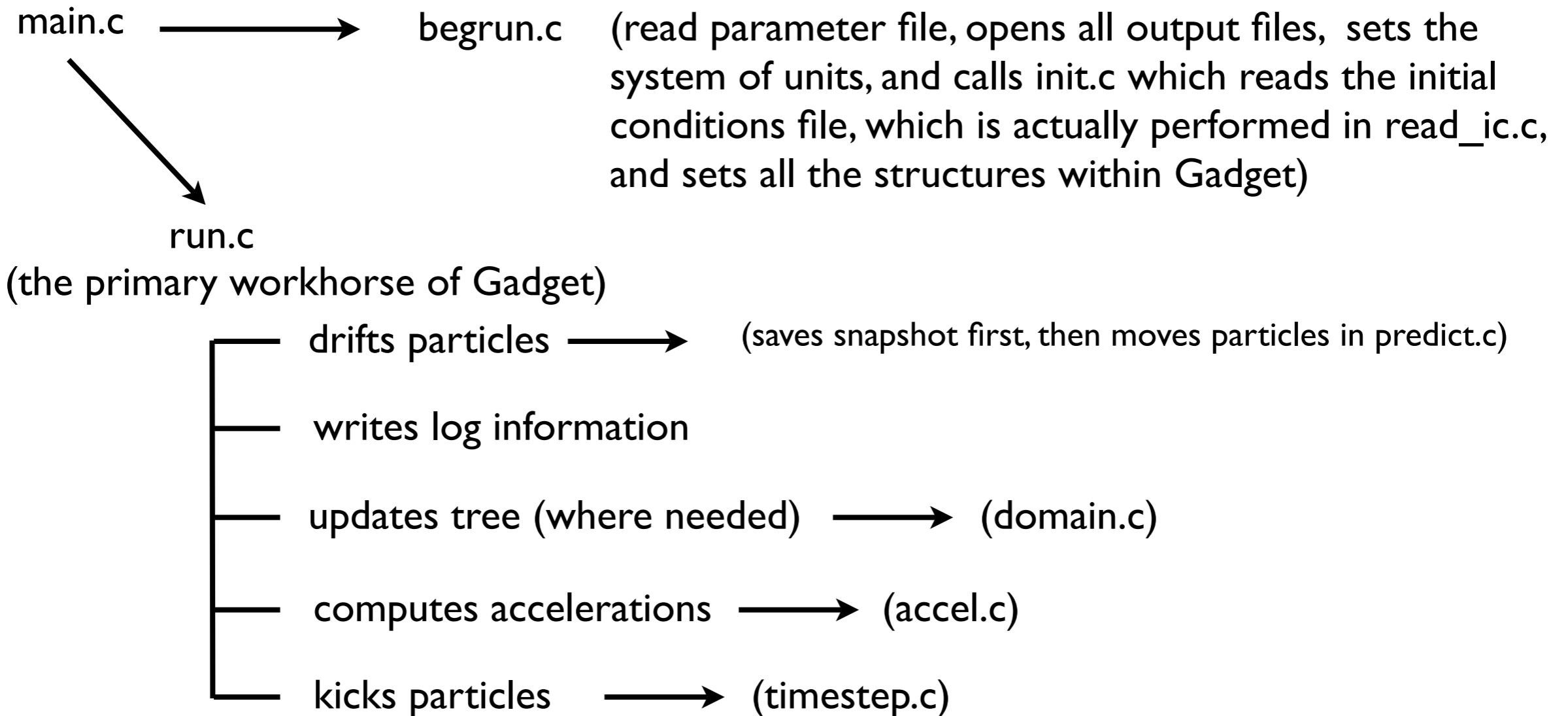
Parameter file options:

% Further parameters of SPH

DesNumNgb	50
MaxNumNgbDeviation	2
ArtBulkViscConst	0.8
InitGasTemp	0
MinGasTemp	0
MinGasHsmLFractional	0.25

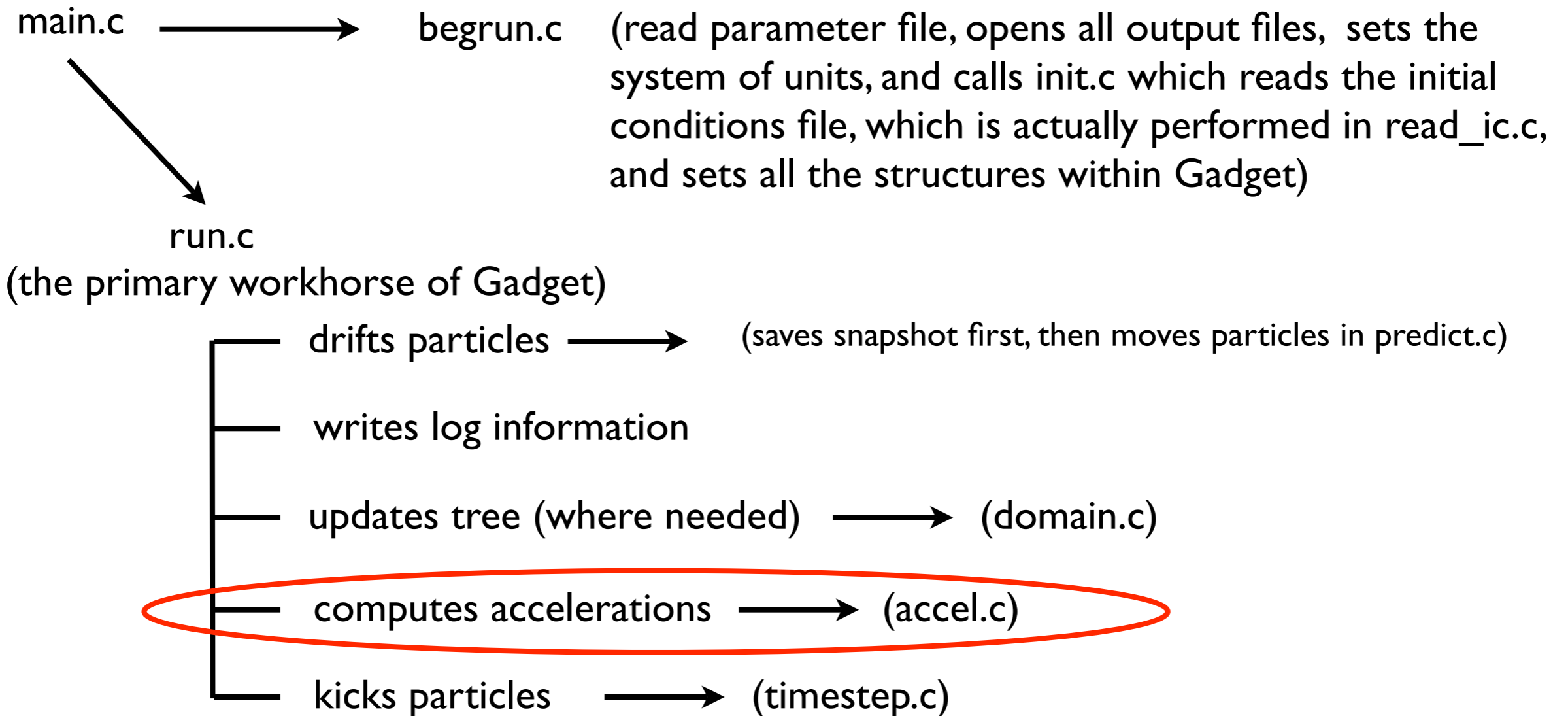
3.6 The steps GADGET takes to accomplish the above

A brief outline of the modules that Gadget uses to perform the aforementioned processes:



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3.6 The steps GADGET takes to accomplish the above

computes accelerations

(accel.c)

- ┌ compute gravitational acceleration in gravtree.c
- ├ determine SPH density in density.c
- └ compute hydrodynamic forces in hydra.c

3.6 The steps GADGET takes to accomplish the above

computes accelerations
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- compute gravitational acceleration in gravtree.c
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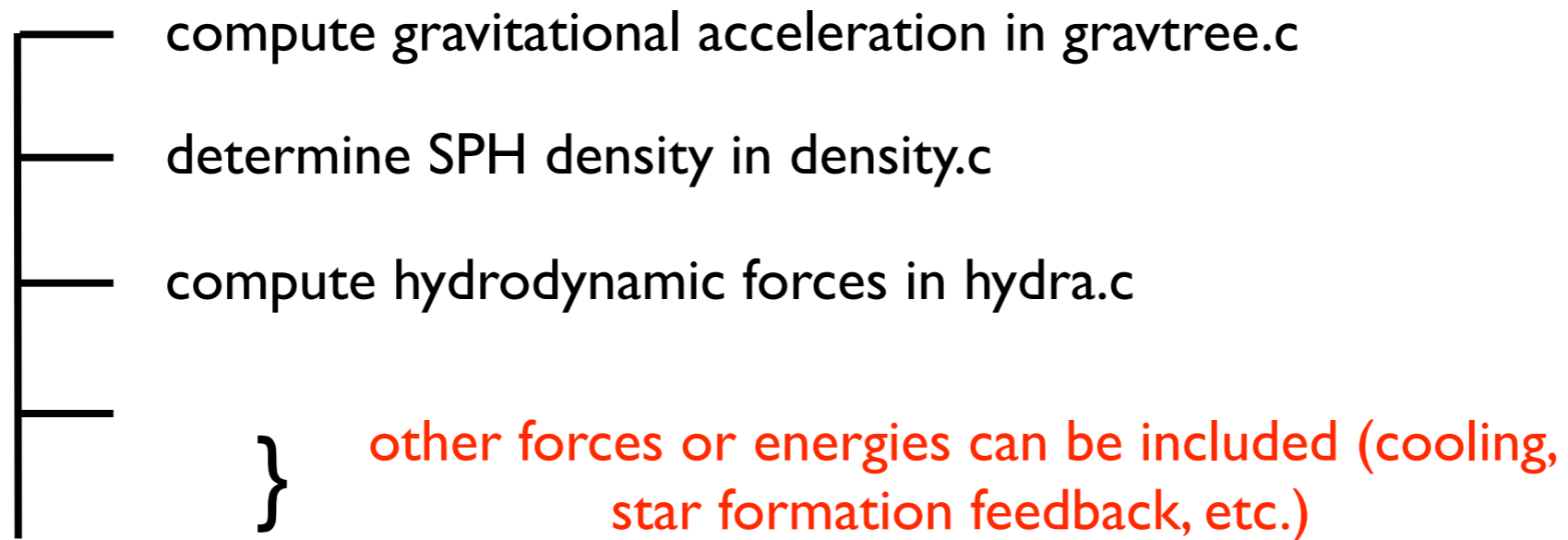
It is fairly straightforward to add a fixed potential to a Gadget simulation:

* gravtree.c/gravity_tree walks tree to compute the gravitational acceleration for each particle and stores this in $P[i].\text{GravAccel}[j]$

* Loop through the particle a second time and add any additional acceleration you desire.

3.6 The steps GADGET takes to accomplish the above

computes accelerations
(accel.c)



3.7 Data Structures within Gadget

There are three primary data structures within Gadget

- * All.(xx) = global variables stored on ALL processors
- * P[i].Pos[j], Vel[j], = particle information, unique to each processor
- * SphP[i].Entropy, Pressure, ... = SPH particle information, unique to each processor

=> see allvars.h for a complete listing of all structure variables

3.8 Cosmological Simulations with Gadget


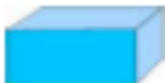
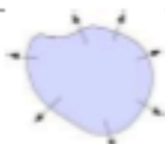



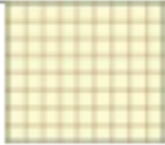
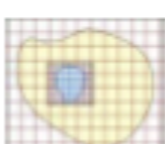


Makefile and parameter settings that need to be changed:

Compile-time options from within the Makefile:

```
#OPT += -DPERIODIC
```

Parameter file options:

```
ComovingIntegrationOn    0
PeriodicBoundariesOn     0
Omega0                   0
OmegaLambda               0
OmegaBaryon               0
HubbleParam               1.0
BoxSize                   0
```

Type of Simulation		Computational methods	Remarks
1	Newtonian space	 Gravity: Tree, SPH (optional), vacuum boundary conditions	OmegaLambda should be set to zero
2	Periodic long box	 No gravity, only SPH, periodic boundary conditions	NOGRAVITY needs to be set, LONG_X/Y/Z may be set to scale the dimensions of the box
3	Cosmological, physical coordinates	 Gravity: Tree, SPH, vacuum boundaries	ComovingIntegrationOn set to zero
4	Cosmological, co-moving coordinates	 Gravity: Tree, SPH, vacuum boundaries	ComovingIntegrationOn set to one
5	Cosmological, co-moving periodic box	 Gravity: Tree with Ewald-correction, SPH, periodic boundaries	PERIODIC needs to be set
6	Cosmological, co-moving coordinates, TreePM	 Gravity: Tree with long range PM, SPH, vacuum boundaries	PMGRID needs to be set
7	Cosmological, co-moving periodic box, TreePM	 Gravity: Tree with long range PM, SPH, periodic boundaries	PERIODIC and PMGRID need to be set
8	Cosmological, co-moving coordinates, TreePM, Zoom	 Gravity: Tree with long-range and intermediate-range PM, SPH, vacuum boundaries	PMGRID and PLACEHIGHRESREGION need to be set
9	Cosmological, periodic comoving box, TreePM, Zoom	 Gravity: Tree with long-range and intermediate-range PM, SPH, periodic boundaries	PERIODIC, PMGRID and PLACEHIGHRESREGION need to be set
10	Newtonian space, TreePM	 Gravity: Tree with long-range PM, SPH, vacuum boundaries	PMGRID needs to be set

3.9 The remaining parameters

The remainder of Gadget compile-time and parameter file options

Compile-time options from within the Makefile:

```
OPT += -DPEANOHILBERT
```

```
OPT += -DWALLCLOCK
```

```
OPT += -DDOUBLEPRECISION
```

```
#OPT += -DDOUBLEPRECISION_FFTW
```

```
#OPT += -DHAVE_HDF5
```

```
OPT += -DOUTPUTPOTENTIAL
```

```
#OPT += -DOUTPUTACCELERATION
```

```
#OPT += -DOUTPUTCHANGE OF ENTROPY
```

```
#OPT += -DOUTPUTTIMESTEP
```

3.9 The remaining parameters

The remainder of Gadget compile-time and parameter file options

Compile-time options from within the Makefile:

OPT += -DPEANOHILBERT

OPT += -DWALLCLOCK

OPT += -DDOUBLEPRECISION

#OPT += -DDOUBLEPRECISION_FFTW

#OPT += -DHAVE_HDF5

OPT += -DOUTPUTPOTENTIAL

#OPT += -DOUTPUTACCELERATION

#OPT += -DOUTPUTCHANGE OF ENTROPY

#OPT += -DOUTPUTTIMESTEP

always recommended

3.9 The remaining parameters

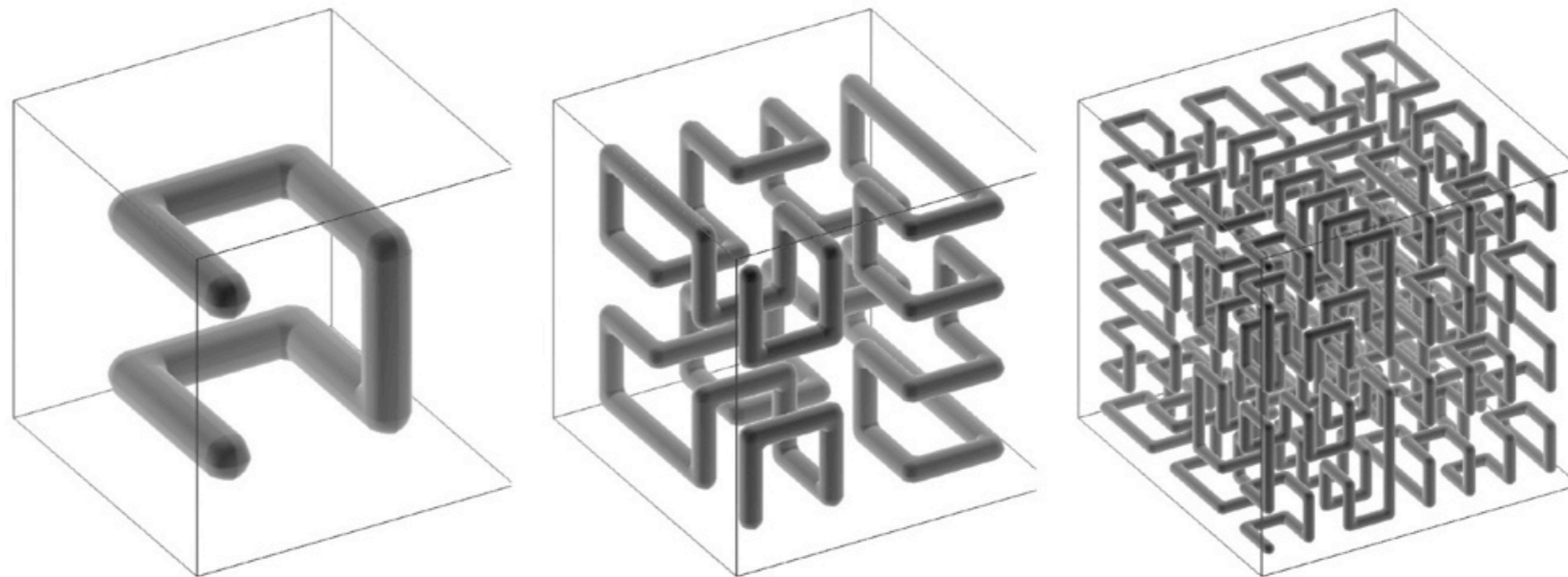
The remainder of Gadget compile-time and parameter file options

Compile-time options from within the Makefile:

```
OPT += -DPEANOHILBERT
```

The space-filling Hilbert curve can be readily generalized to 3D

THE PEANO-HILBERT CURVE



3.9 The remaining parameters

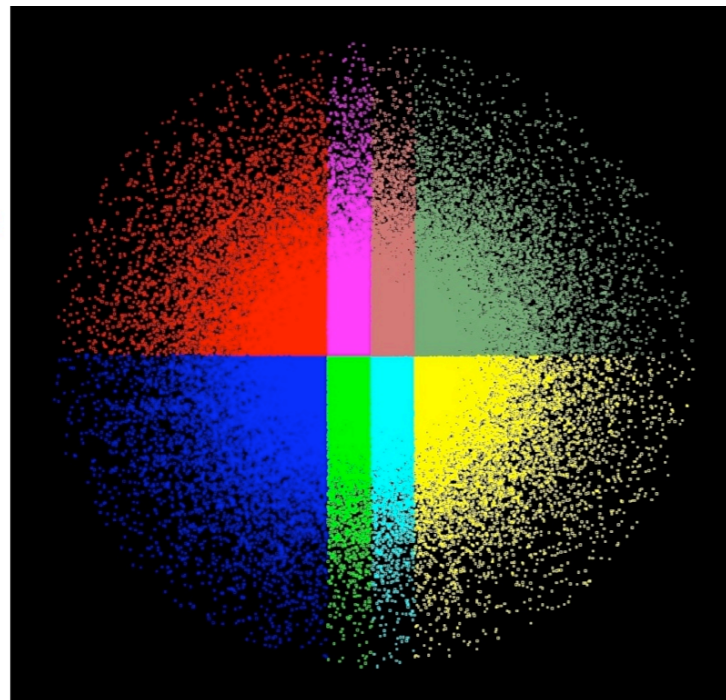
The remainder of Gadget compile-time and parameter file options

Compile-time options from within the Makefile:

```
OPT += -DPEANOHILBERT
```

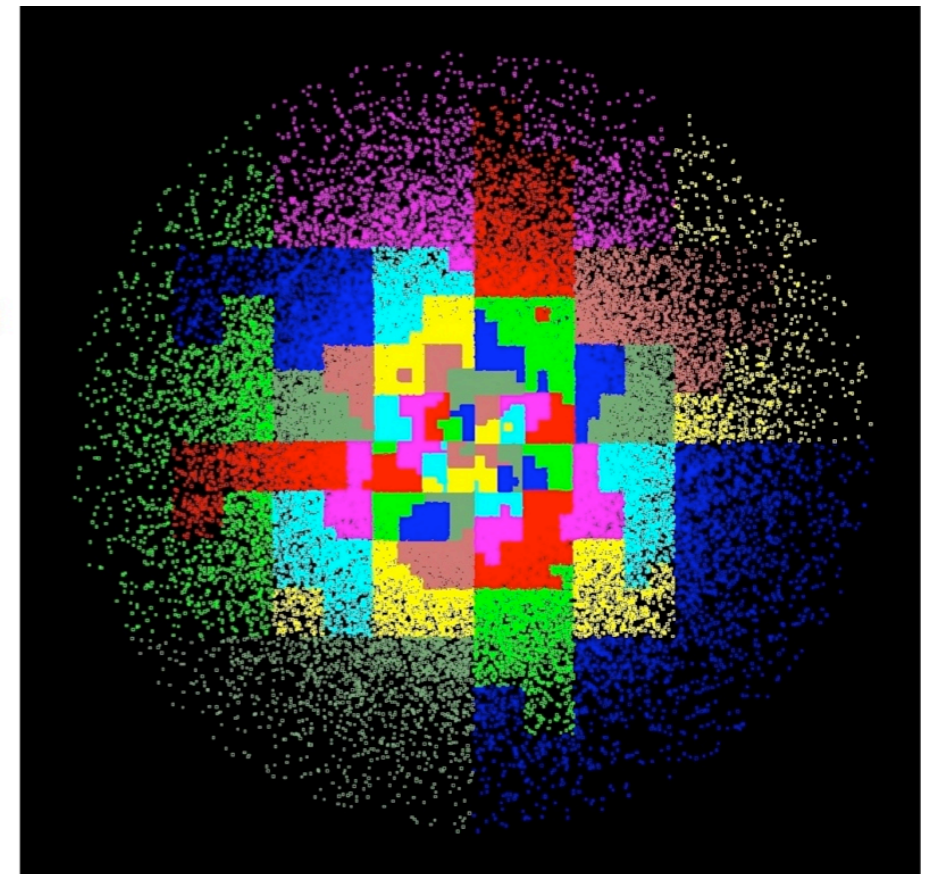
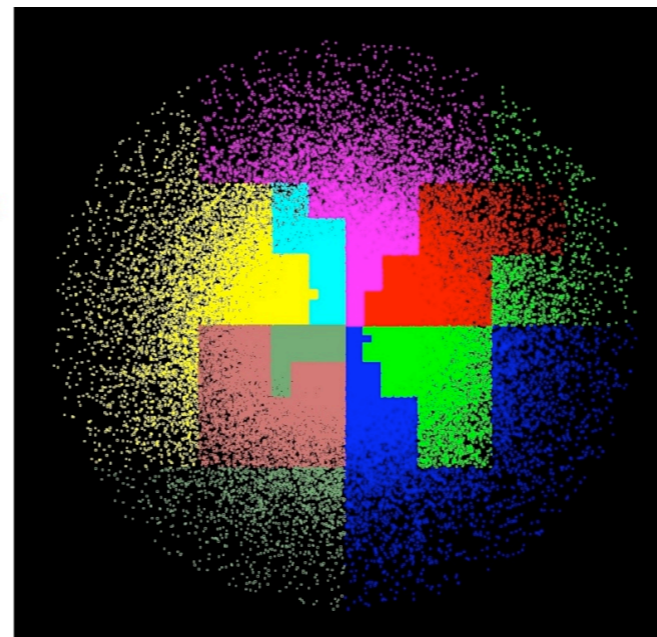
GADGET-1
used a simple
orthogonal
recursive
bisection

EXAMPLE OF
DOMAIN
DECOMPOSITION IN
GADGET-1



GADGET-3
uses a space-
filling Peano-
Hilbert curve
which is more
flexible

EXAMPLE OF
DOMAIN
DECOMPOSITION IN
GADGET-3



3.9 The remaining parameters

The remainder of Gadget compile-time and parameter file options

Parameter file options:

% Relevant files

InitCondFile /home/hipacc-5/MakeDiskGalaxy/Sa.dat
OutputDir /home/hipacc-5/Sa/

EnergyFile energy.txt
InfoFile info.txt
TimingsFile timings.txt
CpuFile cpu.txt

RestartFile restart
SnapshotFileBase snapshot

OutputListFilename parameterfiles/output_list.txt

% Output frequency

TimeBetSnapshot 0.05
TimeOfFirstSnapshot 0

CpuTimeBetRestartFile 1800.0 ; here in seconds
TimeBetStatistics 0.05

NumFilesPerSnapshot 1
NumFilesWrittenInParallel 1

3.9 The remaining parameters

The remainder of Gadget compile-time and parameter file options

Parameter file options:

% Relevant files

InitCondFile /home/hipacc-5/MakeDiskGalaxy/Sa.dat
OutputDir /home/hipacc-5/Sa/

EnergyFile energy.txt
InfoFile info.txt
TimingsFile timings.txt
CpuFile cpu.txt

RestartFile restart
SnapshotFileBase snapshot

OutputListFilename parameterfiles/output_list.txt

% Output frequency

TimeBetSnapshot 0.05
TimeOfFirstSnapshot 0

CpuTimeBetRestartFile 1800.0 ; here in seconds
TimeBetStatistics 0.05

NumFilesPerSnapshot 1
NumFilesWrittenInParallel 1



checkpoint

Restarting from a Checkpoint

PBS batchscript :

```
#!/bin/sh
#PBS -q batch
#PBS -N Sbc
#PBS -l nodes=2:ppn=2
#PBS -o Sbc.out
#PBS -e Sbc.err
#PBS -V
#PBS -M tcox@obs.carnegiescience.edu
#PBS -m abe

cd /home/hipacc-5/Sbc/

mpirun -v -machinefile $PBS_NODEFILE -np 4 ./Gadget2 Sbc.txt > output0.txt
```

add a "1" to restart from the last checkpoint - or you can add "2" to start from the last snapshot, but changes are also needed in the parameter file too



3.9 The remaining parameters

The remainder of Gadget compile-time and parameter file options

Parameter file options:

```
% CPU time -limit
```

```
TimeLimitCPU      36000  % = 10 hours  
ResubmitOn        0  
ResubmitCommand   my-scriptfile
```

3.9 The remaining parameters

The remainder of Gadget compile-time and parameter file options

Parameter file options:

```
ICFormat          1    }    with          #OPT    +=    -DHAVE_HDF5
SnapFormat        1
```

```
% Characteristics of run
```

```
TimeBegin         0.0    % Begin of the simulation
TimeMax           1.0    % End of the simulation
```

3.9 The remaining parameters

The remainder of Gadget compile-time and parameter file options

Parameter file options:

% Memory allocation

PartAllocFactor	3.5	
TreeAllocFactor	1.5	
BufferSize	50	% in MByte

% System of units

UnitLength_in_cm	3.085678e21	; 1.0 kpc
UnitMass_in_g	1.989e43	; 1.0e10 solar masses
UnitVelocity_in_cm_per_s	1e5	; 1 km/sec
GravityConstantInternal	0	

3.10 Odds and Ends

Questions?

How are any tests going?