## Intro Physics Semester I

Name:
Homework 7: Energy: One or two or no full answer questions will be marked. There will also be a mark for completeness. Homeworks are due usually the day after the chapter they are for is finished. Solutions will be posted soon thereafter. The solutions are intended to be (but not necessarily are) super-perfect and often go beyond a fully correct answer.


1. Five special forces in physics are:
a) gravitational force, normal force, tension, friction force, and the linear force (the Hooke's law force).
b) gravitational force, normal force, tension, friction force, and left force (the Captain Hooke's law force).
c) gravitational force, normal force, tension, friction force, and right force.
d) gravitational force, normal force, tension, friction force, and air force.
e) gravitational force, normal force, tension, friction force, and the Force.
2. In one dimension, the linear force formula is:
a) $F=-k x^{2}$.
b) $F=k x$.
c) $F=-k x$.
d) $F=k x^{2}$.
e) $F=k / x^{2}$.
3. If you double the force constant of a simple harmonic oscillator, the period changes by a factor of:
a) $1 / 2$.
b) $\sqrt{2}$.
c) 2 .
d) $1 / \sqrt{2}$.
e) $2 / 3$.
4. "Let's play Jeopardy! For $\$ 100$, the answer is: Admitting that all short definitions of it are inadequate, one can suggest that it is the conserved essence of structure and transformability. 'Converved' means that the quantity that is neither created nor destroyed. In this case, all forms of the quantity must be summed to have conservation in general though in special cases conservation may hold for a subset of forms. 'Essence of structure' means that the quantity is a general measure of structure, but it does not describe details of structure. 'Structure' is used here in a very general sense to mean the ordering of objects, particles, fields, and motions. 'Essence of transformability' means that the quantity can be transformed into different forms of itself and that all changes in the amounts of the forms result in changes in structure. If you have some of the quantity, transformations are possible. Knowing which ones occur requires more detailed information."

What is $\qquad$ , Alex?
a) force
b) momentum
c) angular momentum
d) potential
e) energy
5. "Let's play Jeopardy! For $\$ 100$, the answer is: A useful, but incomplete definition, is the quantified capacity for change."

What is $\qquad$ Alex?
a) momentum
b) force
c) potential
d) energy
e) aspiration
6. "Let's play Jeopardy! For $\$ 100$, the answer is: It has been described as that property of something that enables that something to do work."

What is $\qquad$ , Alex?
a) inevitability
b) noise
c) tension
d) gravity
e) energy
7. The principle of conservation of energy is that energy is never:
a) adequately defined.
b) destroyed, but can be created.
c) created or destroyed.
d) created, but can be destroyed.
e) destroyed.
8. The total energy of a closed system (i.e., a system which nothing enters or leaves) is:
a) conserved.
b) annihilated.
c) created.
d) combusted.
e) eviscerated.
9. The physical dimensions of energy are:
a) $\mathrm{ML}^{2} / \mathrm{T}^{2}$.
b) $\mathrm{ML} / \mathrm{T}^{2}$.
c) $\mathrm{ML}^{2}$.
d) $\mathrm{ML}^{2} / \mathrm{T}$.
e) $M / T^{2}$.
10. The standard SI unit of energy and of work is the:
a) joule (J).
b) newton (N).
c) kelvin (K).
d) bassingthorp (B).
e) trufflehunter (T).
11. That one has enough energy for a certain job or transformation that requires energy $E$ is a
$\qquad$ condition, but NOT a $\qquad$ condition for the job or transformation.
a) necessary; sufficient
b) sufficient; necessary
c) inevitable; necessarily so
d) harmonious; ceremonious
e) forbidden; given
12. "Let's play Jeopardy! For $\$ 100$, the answer is: Because of its protean nature, energy is very much like this thing in everyday human life which, however, unlike energy is not conserved."
What is/are $\qquad$ , Alex?
a) furs
b) assignats
c) shells
d) gold
e) money
13. "Let's play Jeopardy! For $\$ 100$, the answer is: In physics, it is a macroscopic process of energy transfer."

What is $\qquad$ , Alex?
a) energy
b) work
c) force
d) weight
e) sloth
14. The differential work formula is:
a) $d W=\vec{F} d \vec{s}$.
b) $d W=\vec{F} \cdot d \vec{s}$.
c) $d W=\vec{F} / d \vec{s}$.
d) $d W=F d s$.
e) $d W=\vec{F} \times d \vec{s}$.
15. A constant force $\vec{F}$ acts on a body while that body moves a distance $\Delta \vec{r}$. The work $W$ done on the body by the force is given by:
a) $W=\vec{F} / \Delta \vec{r}$.
b) $W=\vec{F}$.
c) $W=\vec{F} \cdot \Delta \vec{r}$.
d) $W=\vec{F} \cdot \vec{F} \cdot \Delta \vec{r}$.
e) $W=\vec{F} \cdot \Delta \vec{r} \cdot \Delta \vec{r}$.
16. How much work is done by a lifter lifting a 100 kg load straight upward 10 m without acceleration?
a) 9800 J .
b) 100 J .
c) 1000 J .
d) 10 J .
e) 980 J .
17. A person holds 10 kg grouse at 2.0 m above the ground for 30 s . How much macroscopic net work is done by the person on the grouse?
a) 600 J .
b) 20 J .
c) 300 J .
d) 60 J .
e) 0 J .
18. Kinetic energy is:
a) the energy of POSITION with formula $K E=m g y . \quad$ b) the energy of MOTION with formula $K E=m g y$. c) the energy of MOTION with formula $K E=(1 / 2) m v^{2}$. d) the energy of POSITION with formula $K E=(1 / 2) m v^{2} . \quad$ e) heat energy.
19. The work-kinetic-energy theorem is:
a) $K E=\frac{1}{2} m v^{2}$.
b) $\Delta E=W_{\text {non }}$.
c) $\Delta K E=W$.
d) $\Delta K E=\frac{1}{2} W$.
e) $\Delta K E=\frac{1}{2} m v^{2}$.
20. A moving object has initial $K E=100 \mathrm{~J}$ and is subjected to a friction force of magnitude 2 N and no other forces. How far does the object go before coming to a stop?
a) 100 m .
b) 2 m .
c) 1000 m .
d) 50 m .
e) 0 m .
21. We will now the derive the work-kinetic energy theorem in little-bitty steps. Recall the work-kineticenergy theorem is

$$
W=\Delta K E
$$

where $W$ is the work done by the net external force acting on a body and $\Delta K E$ is the change in the body's center-of-mass kinetic energy.
a) Write down the differential definition of work.
b) Write down the integral definition of work with unspecified endpoints.
c) Write down the formula for the work between points $\vec{A}$ and $\vec{B}$ done by net external force on a body and make use of Newton's 2nd law to rewrite this formula in terms of the body's center-of-mass acceleration.
d) Prove that

$$
\vec{a} \cdot \vec{v}=\frac{1}{2} \frac{d v^{2}}{d t}
$$

e) Given that $d \vec{s}=\vec{v} d t$, now prove the work-kinetic-energy theorem
22. You are pushing a 60 kg block across a frictionless surface - which is no mean feat in itself.
a) You exert 100 N of force in the direction of motion and push the block for 30 m . How much work have you done on the block? Show how you got your answer.
b) Assuming you start the block from REST and no other forces do work, what is the final kinetic energy and speed of the block? Show how you got your answer.
23. Power in physics is the rate per unit time of energy transferred or transformed. This is a general definition independent of the where the energy is coming from and where it is going too. If work is the energy transfer process, the differential work formula $d W=\vec{F} \cdot d \vec{s}$ leads immediately to the power formula for work:

$$
P=\frac{d W}{d t}=\vec{F} \cdot \frac{d \vec{s}}{d t}=\vec{F} \cdot \vec{v}
$$

where $\vec{v}$ is velocity (i.e., center-of-mass velocity) of the displaced system. The MKS unit of work is the joule per second $(J / s)$ which has its own name: the familear watt with symbol (W).

Now that we've preambled, there is a frictionless block of ice of 50 kg on an incline of $30^{\circ}$. A worker pushes the block straight up the incline at a CONSTANT velocity of $3.0 \mathrm{~m} / \mathrm{s}$.
a) What is the power output (i.e., rate of work done) by the worker?
b) What is the power output by gravity?
c) What is the power output by the normal force? Why?

## Equation Sheet for Introductory Physics Calculus-Based

This equation sheet is intended for students writing tests or reviewing material. Therefore it is neither intended to be complete nor completely explicit. There are fewer symbols than variables, and so some symbols must be used for different things: context must distinguish.

The equations are mnemonic. Students are expected to understand how to interpret and use them.

## 1 Constants

$$
\begin{aligned}
c & =2.99792458 \times 10^{8} \mathrm{~m} / \mathrm{s} \approx 2.998 \times 10^{8} \mathrm{~m} / \mathrm{s} \approx 3 \times 10^{8} \mathrm{~m} / \mathrm{s} \approx 1 \mathrm{lyr} / \mathrm{yr} \approx 1 \mathrm{ft} / \mathrm{ns} \quad \text { exact by definition } \\
e & =1.602176487(40) \times 10^{-19} \mathrm{C} \\
G & =6.67428(67) \times 10^{-11} \mathrm{~N} \mathrm{~m}^{2} / \mathrm{kg}^{2} \quad(2006, \mathrm{CODATA}) \\
g & =9.8 \mathrm{~m} / \mathrm{s}^{2} \quad \text { fiducial value } \\
k & =\frac{1}{4 \pi \varepsilon_{0}}=8.987551787 \ldots \times 10^{9} \approx 8.99 \times 10^{9} \approx 10^{10} \mathrm{~N} \mathrm{~m}^{2} / \mathrm{C}^{2} \text { exact by definition } \\
k_{\text {Boltzmann }} & =1.3806504(24) \times 10^{-23} \mathrm{~J} / \mathrm{K}=0.8617343(15) \times 10^{-4} \mathrm{eV} / \mathrm{K} \approx 10^{-4} \mathrm{eV} / \mathrm{K} \\
m_{e} & =9.10938215(45) \times 10^{-31} \mathrm{~kg}=0.510998910(13) \mathrm{MeV} \\
m_{p} & =1.672621637(83) \times 10^{-27} \mathrm{~kg}=938.272013(23), \mathrm{MeV} \\
\varepsilon_{0} & =\frac{1}{\mu_{0} c^{2}}=8.8541878176 \ldots \times 10^{-12} \mathrm{C}^{2} /\left(\mathrm{N} \mathrm{~m}^{2}\right) \approx 10^{-11} \quad \text { vacuum permittivity (exact by definition) } \\
\mu_{0} & =4 \pi \times 10^{-7} \mathrm{~N} / \mathrm{A}^{2} \quad \text { exact by definition }
\end{aligned}
$$

2 Geometrical Formulae

$$
\begin{gathered}
C_{\mathrm{cir}}=2 \pi r \quad A_{\mathrm{cir}}=\pi r^{2} \quad A_{\mathrm{sph}}=4 \pi r^{2} \quad V_{\mathrm{sph}}=\frac{4}{3} \pi r^{3} \\
\Omega_{\mathrm{sphere}}=4 \pi \quad d \Omega=\sin \theta d \theta d \phi
\end{gathered}
$$

3 Trigonometry Formulae

$$
\begin{gathered}
\frac{x}{r}=\cos \theta \quad \frac{y}{r}=\sin \theta \quad \frac{y}{x}=\tan \theta=\frac{\sin \theta}{\cos \theta} \quad \cos ^{2} \theta+\sin ^{2} \theta=1 \\
\csc \theta=\frac{1}{\sin \theta} \quad \sec \theta=\frac{1}{\cos \theta} \quad \cot \theta=\frac{1}{\tan \theta} \\
c^{2}=a^{2}+b^{2} \quad c=\sqrt{a^{2}+b^{2}-2 a b \cos \theta_{c}} \quad \frac{\sin \theta_{a}}{a}=\frac{\sin \theta_{b}}{b}=\frac{\sin \theta_{c}}{c} \\
f(\theta)=f\left(\theta+360^{\circ}\right) \\
\sin \left(\theta+180^{\circ}\right)=-\sin (\theta) \quad \cos \left(\theta+180^{\circ}\right)=-\cos (\theta) \quad \tan \left(\theta+180^{\circ}\right)=\tan (\theta) \\
\sin (-\theta)=-\sin (\theta) \quad \cos (-\theta)=\cos (\theta) \quad \tan (-\theta)=-\tan (\theta)
\end{gathered}
$$

$$
\begin{aligned}
& \sin \left(\theta+90^{\circ}\right)=\cos (\theta) \quad \cos \left(\theta+90^{\circ}\right)=-\sin (\theta) \quad \tan \left(\theta+90^{\circ}\right)=-\tan (\theta) \\
& \sin \left(180^{\circ}-\theta\right)=\sin (\theta) \quad \cos \left(180^{\circ}-\theta\right)=-\cos (\theta) \quad \tan \left(180^{\circ}-\theta\right)=-\tan (\theta) \\
& \sin \left(90^{\circ}-\theta\right)=\cos (\theta) \quad \cos \left(90^{\circ}-\theta\right)=\sin (\theta) \quad \tan \left(90^{\circ}-\theta\right)=\frac{1}{\tan (\theta)}=\cot (\theta) \\
& \sin (a+b)=\sin (a) \cos (b)+\cos (a) \sin (b) \quad \cos (a+b)=\cos (a) \cos (b)-\sin (a) \sin (b) \\
& \sin (2 a)=2 \sin (a) \cos (a) \quad \cos (2 a)=\cos ^{2}(a)-\sin ^{2}(a) \\
& \sin (a) \sin (b)=\frac{1}{2}[\cos (a-b)-\cos (a+b)] \quad \cos (a) \cos (b)=\frac{1}{2}[\cos (a-b)+\cos (a+b)] \\
& \sin (a) \cos (b)=\frac{1}{2}[\sin (a-b)+\sin (a+b)] \\
& \sin ^{2} \theta=\frac{1}{2}[1-\cos (2 \theta)] \quad \cos ^{2} \theta=\frac{1}{2}[1+\cos (2 \theta)] \quad \sin (a) \cos (a)=\frac{1}{2} \sin (2 a) \\
& \cos (x)-\cos (y)=-2 \sin \left(\frac{x+y}{2}\right) \sin \left(\frac{x-y}{2}\right) \\
& \cos (x)+\cos (y)=2 \cos \left(\frac{x+y}{2}\right) \cos \left(\frac{x-y}{2}\right) \\
& \sin (x)+\sin (y)=2 \sin \left(\frac{x+y}{2}\right) \cos \left(\frac{x-y}{2}\right)
\end{aligned}
$$

## 4 Approximation Formulae

$$
\begin{aligned}
\frac{\Delta f}{\Delta x} \approx \frac{d f}{d x} \quad \frac{1}{1-x} \approx 1+x:(x \ll 1) \\
\sin \theta \approx \theta \quad \tan \theta \approx \theta \quad \cos \theta \approx 1-\frac{1}{2} \theta^{2} \quad \text { all for } \theta \ll 1
\end{aligned}
$$

## 5 Quadratic Formula

If

$$
0=a x^{2}+b x+c, \quad \text { then } \quad x=\frac{-b \pm \sqrt{b^{2}-4 a c}}{2 a}=-\frac{b}{2 a} \pm \sqrt{\left(\frac{b}{2 a}\right)^{2}-\frac{c}{a}}
$$

6 Vector Formulae

$$
\begin{gathered}
a=|\vec{a}|=\sqrt{a_{x}^{2}+a_{y}^{2}} \quad \theta=\tan ^{-1}\left(\frac{a_{y}}{a_{x}}\right)+\pi ? \quad \vec{a}+\vec{b}=\left(a_{x}+b_{x}, a_{y}+b_{y}\right) \\
a=|\vec{a}|=\sqrt{a_{x}^{2}+a_{y}^{2}+a_{z}^{2}} \quad \phi=\tan ^{-1}\left(\frac{a_{y}}{a_{x}}\right)+\pi ? \quad \theta=\cos ^{-1}\left(\frac{a_{z}}{a}\right) \\
\vec{a}+\vec{b}=\left(a_{x}+b_{x}, a_{y}+b_{y}, a_{z}+b_{z}\right) \\
\vec{a} \cdot \vec{b}=a b \cos \theta=a_{x} b_{x}+a_{y} b_{y}+a_{z} b_{z} \\
\vec{c}=\vec{a} \times \vec{b}=a b \sin (\theta) \hat{c}=\left(a_{y} b_{z}-b_{y} a_{z}, a_{z} b_{x}-b_{z} a_{x}, a_{x} b_{y}-b_{x} a_{y}\right)
\end{gathered}
$$

7 Differentiation and Integration Formulae

$$
\frac{d\left(x^{p}\right)}{d x}=p x^{p-1} \quad \text { except for } p=0 ; \quad \frac{d\left(x^{0}\right)}{d x}=0 \quad \frac{d(\ln |x|)}{d x}=\frac{1}{x}
$$

Taylor's series $\quad f(x)=\sum_{n=0}^{\infty} \frac{\left(x-x_{0}\right)^{n}}{n!} f^{(n)}\left(x_{0}\right)$

$$
=f\left(x_{0}\right)+\left(x-x_{0}\right) f^{(1)}\left(x_{0}\right)+\frac{\left(x-x_{0}\right)^{2}}{2!} f^{(2)}\left(x_{0}\right)+\frac{\left(x-x_{0}\right)^{3}}{3!} f^{(3)}\left(x_{0}\right)+\ldots
$$

$$
\int_{a}^{b} f(x) d x=\left.F(x)\right|_{a} ^{b}=F(b)-F(a) \quad \text { where } \quad \frac{d F(x)}{d x}=f(x)
$$

$$
\int x^{n} d x=\frac{x^{n+1}}{n+1} \quad \text { except for } n=-1 ; \quad \int \frac{1}{x} d x=\ln |x|
$$

## 8 One-Dimensional Kinematics

$$
\begin{gathered}
v_{\mathrm{avg}}=\frac{\Delta x}{\Delta t} \quad v=\frac{d x}{d t} \quad a_{\mathrm{avg}}=\frac{\Delta v}{\Delta t} \quad a=\frac{d v}{d t}=\frac{d^{2} x}{d t^{2}} \\
v=a t+v_{0} \quad x=\frac{1}{2} a t^{2}+v_{0} t+x_{0} \quad v^{2}=v_{0}^{2}+2 a\left(x-x_{0}\right) \\
x=\frac{1}{2}\left(v_{0}+v\right) t+x_{0} \quad x=-\frac{1}{2} a t^{2}+v t+x_{0} \quad g=9.8 \mathrm{~m} / \mathrm{s}^{2}
\end{gathered}
$$

$$
\begin{array}{r}
x_{\text {rel }}=x_{2}-x_{1} \quad v_{\text {rel }}=v_{2}-v_{1} \quad a_{\text {rel }}=a_{2}-a_{1} \\
x^{\prime}=x-v_{\text {frame }} t \quad v^{\prime}=v-v_{\text {frame }} \quad a^{\prime}=a
\end{array}
$$

9 Two- and Three-Dimensional Kinematics: General

$$
\vec{v}_{\text {avg }}=\frac{\Delta \vec{r}}{\Delta t} \quad \vec{v}=\frac{d \vec{r}}{d t} \quad \vec{a}_{\mathrm{avg}}=\frac{\Delta \vec{v}}{\Delta t} \quad \vec{a}=\frac{d \vec{v}}{d t}=\frac{d^{2} \vec{r}}{d t^{2}}
$$

## 10 Projectile Motion

$$
\begin{gathered}
x=v_{x, 0} t \quad y=-\frac{1}{2} g t^{2}+v_{y, 0} t+y_{0} \quad v_{x, 0}=v_{0} \cos \theta \quad v_{y, 0}=v_{0} \sin \theta \\
t=\frac{x}{v_{x, 0}}=\frac{x}{v_{0} \cos \theta} \quad y=y_{0}+x \tan \theta-\frac{x^{2} g}{2 v_{0}^{2} \cos ^{2} \theta} \\
x_{\text {for } y \max }=\frac{v_{0}^{2} \sin \theta \cos \theta}{g} \quad y_{\text {max }}=y_{0}+\frac{v_{0}^{2} \sin ^{2} \theta}{2 g} \\
x\left(y=y_{0}\right)=\frac{2 v_{0}^{2} \sin \theta \cos \theta}{g}=\frac{v_{0}^{2} \sin (2 \theta)}{g} \quad \theta_{\text {for } \max }=\frac{\pi}{4} \quad x_{\max }\left(y=y_{0}\right)=\frac{v_{0}^{2}}{g} \\
x(\theta=0)= \pm v_{0} \sqrt{\frac{2\left(y_{0}-y\right)}{g}} \quad t(\theta=0)=\sqrt{\frac{2\left(y_{0}-y\right)}{g}}
\end{gathered}
$$

11 Relative Motion

$$
\vec{r}=\vec{r}_{2}-\vec{r}_{1} \quad \vec{v}=\vec{v}_{2}-\vec{v}_{1} \quad \vec{a}=\vec{a}_{2}-\vec{a}_{1}
$$

12 Polar Coordinate Motion and Uniform Circular Motion

$$
\begin{gathered}
\omega=\frac{d \theta}{d t} \quad \alpha=\frac{d \omega}{d t}=\frac{d^{2} \theta}{d t^{2}} \\
\vec{r}=r \hat{r} \quad \vec{v}=\frac{d \vec{r}}{d t}=\frac{d r}{d t} \hat{r}+r \omega \hat{\theta} \quad \vec{a}=\frac{d^{2} \vec{r}}{d t^{2}}=\left(\frac{d^{2} r}{d t^{2}}-r \omega^{2}\right) \hat{r}+\left(r \alpha+2 \frac{d r}{d t} \omega\right) \hat{\theta} \\
\vec{v}=r \omega \hat{\theta} \quad v=r \omega \quad a_{\tan }=r \alpha \\
\vec{a}_{\text {centripetal }}=-\frac{v^{2}}{r} \hat{r}=-r \omega^{2} \hat{r} \quad a_{\text {centripetal }}=\frac{v^{2}}{r}=r \omega^{2}=v \omega
\end{gathered}
$$

## 13 Very Basic Newtonian Physics

$$
\begin{aligned}
& \vec{r}_{\mathrm{cm}}=\frac{\sum_{i} m_{i} \vec{r}_{i}}{m_{\mathrm{total}}}=\frac{\sum_{\mathrm{sub}} m_{\mathrm{sub}} \vec{r}_{\mathrm{cm} \mathrm{sub}}}{m_{\text {total }}} \quad \vec{v}_{\mathrm{cm}}=\frac{\sum_{i} m_{i} \vec{v}_{i}}{m_{\text {total }}} \quad \vec{a}_{\mathrm{cm}}=\frac{\sum_{i} m_{i} \vec{a}_{i}}{m_{\text {total }}} \\
& \vec{r}_{\mathrm{cm}}=\frac{\int_{V} \rho(\vec{r}) \vec{r} d V}{m_{\text {total }}} \\
& \vec{F}_{\text {net }}=m \vec{a} \quad \vec{F}_{21}=-\vec{F}_{12} \quad F_{g}=m g \quad g=9.8 \mathrm{~m} / \mathrm{s}^{2} \\
& \vec{F}_{\text {normal }}=-\vec{F}_{\text {applied }} \quad F_{\text {linear }}=-k x \\
& f_{\text {normal }}=\frac{T}{r} \quad T=T_{0}-F_{\text {parallel }}(s) \quad T=T_{0} \\
& F_{\mathrm{f} \text { static }}=\min \left(F_{\text {applied }}, F_{\mathrm{f} \text { static max }}\right) \quad F_{\mathrm{f} \text { static max }}=\mu_{\text {static }} F_{\mathrm{N}} \quad F_{\mathrm{f} \text { kinetic }}=\mu_{\text {kinetic }} F_{\mathrm{N}} \\
& v_{\text {tangential }}=r \omega=r \frac{d \theta}{d t} \quad a_{\text {tangential }}=r \alpha=r \frac{d \omega}{d t}=r \frac{d^{2} \theta}{d t^{2}} \\
& \vec{a}_{\text {centripetal }}=-\frac{v^{2}}{r} \hat{r} \quad \vec{F}_{\text {centripetal }}=-m \frac{v^{2}}{r} \hat{r} \\
& F_{\mathrm{drag}, \operatorname{lin}}=b v \quad v_{\mathrm{T}}=\frac{m g}{b} \quad \tau=\frac{v_{\mathrm{T}}}{g}=\frac{m}{b} \quad v=v_{\mathrm{T}}\left(1-e^{-t / \tau}\right) \\
& F_{\text {drag,quad }}=b v^{2}=\frac{1}{2} C \rho A v^{2} \quad v_{\mathrm{T}}=\sqrt{\frac{m g}{b}}
\end{aligned}
$$

## 14 Energy and Work

$$
\begin{gathered}
d W=\vec{F} \cdot d \vec{s} \quad W=\int \vec{F} \cdot d \vec{s} \quad K E=\frac{1}{2} m v^{2} \quad E_{\text {mechanical }}=K E+P E \\
P_{\mathrm{avg}}=\frac{\Delta W}{\Delta t} \quad P=\frac{d W}{d t} \quad P=\vec{F} \cdot \vec{v}
\end{gathered}
$$

$\Delta K E=W_{\text {net }} \quad \Delta P E_{\text {of a conservative force }}=-W_{\text {by a conservative force }} \quad \Delta E=W_{\text {nonconservative }}$

$$
F=-\frac{d P E}{d x} \quad \vec{F}=-\nabla P E \quad P E=\frac{1}{2} k x^{2} \quad P E=m g y
$$

